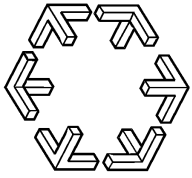


Memory Management for Lock-Free Concurrent Data-structures

Anders Gidenstam

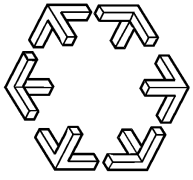
PostDoc,

AG1, Max-Planck-Institut für Informatik



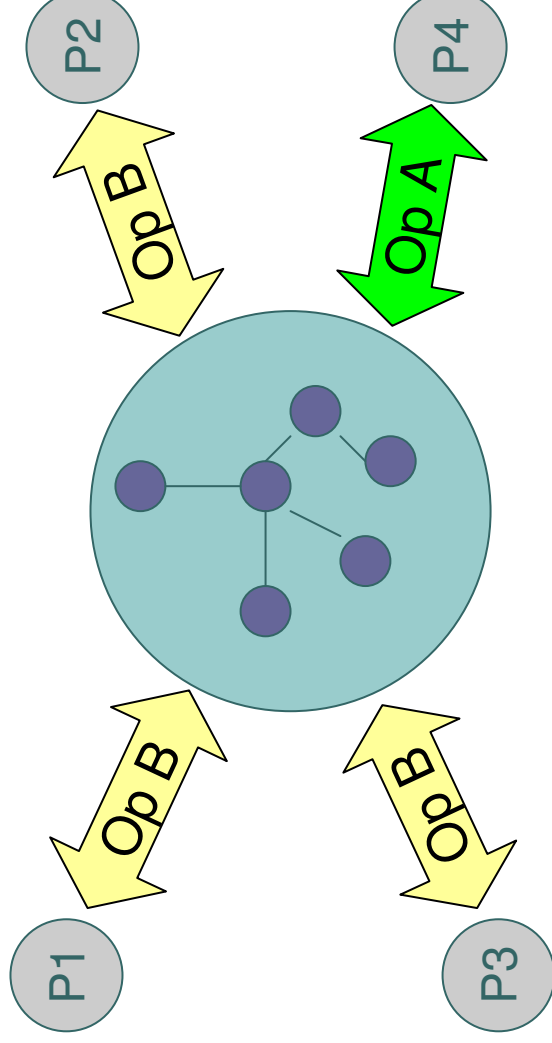
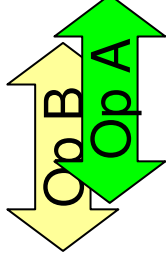
Outline

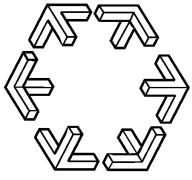
- Introduction to non-blocking algorithms
 - System model
 - Correctness criteria
 - Progress guarantees
 - Motivating example
- The lock-free memory reclamation problem
 - Solutions
 - LFMR [Gidenstam, Papatriantafilou, Sundell & Tsigas. I-SPAN 2005]
 - Idea
 - Properties
- What's out there: Some lock-free data-structures
- Current work



Concurrent Shared Memory Data-structures

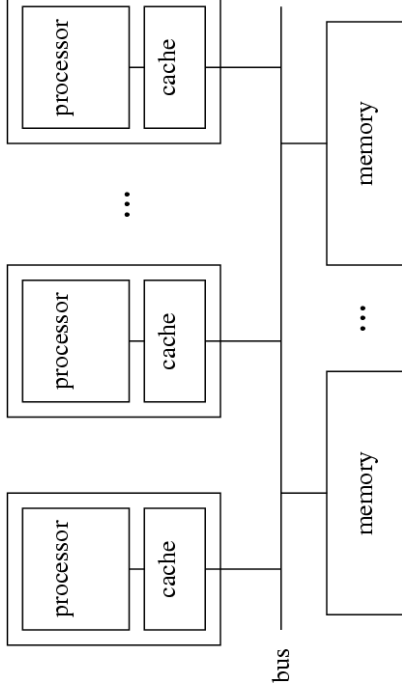
- Object in shared memory
 - Supports some set of operations (ADT)
 - Concurrent access by many processes/threads
 - Useful to e.g.
 - Exchange data between threads
 - Coordinate thread activities

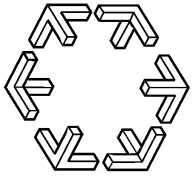




System model

- Processes / threads
 - Asynchronous
 - Each executes a sequence of instructions
- Shared memory
 - Processes can read/write single memory words atomically
 - Hardware synchronization primitives/instructions
 - Compare-and-Swap(address, old, new)
 - Atomic read-modify-write (i.e. a critical section of one instruction)
 - Load-Linked(address) / Store-Conditional(address, new)

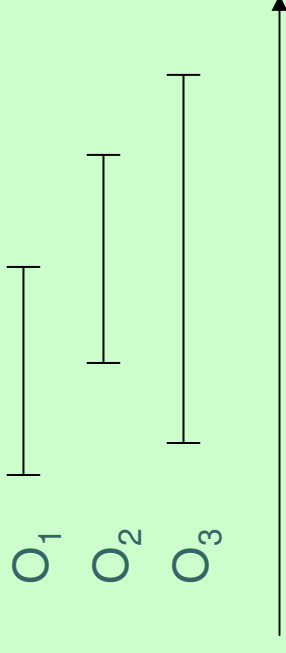


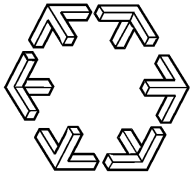


Correctness of a concurrent object

- Desired semantics of a shared data object

- Linearizability [Herlihy & Wing, 1990]
 - For each operation invocation there must be one single time instant during its duration where the operation appears to take effect.
 - The observed effects should be consistent with a sequential execution of the operations in that order.

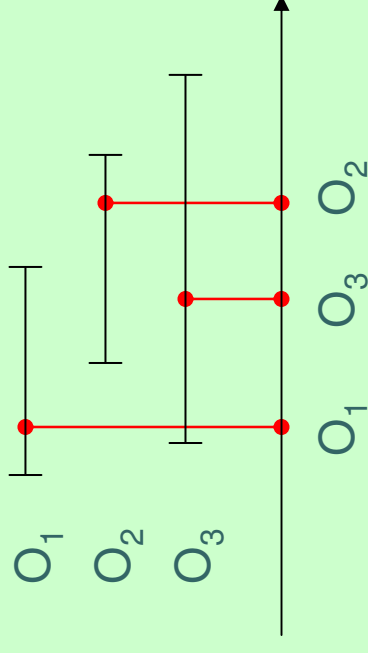


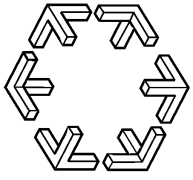


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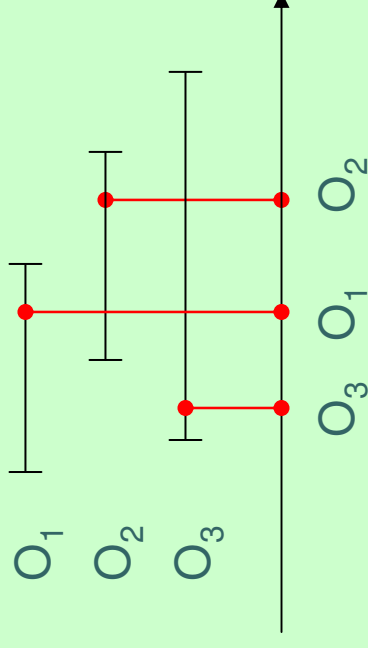


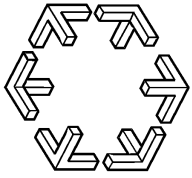


Correctness of a concurrent object

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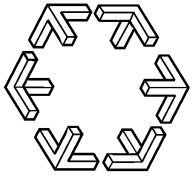
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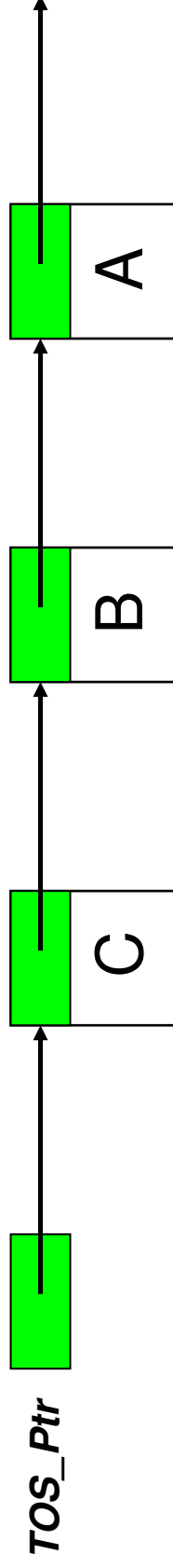
Progress Guarantees

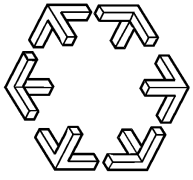
- **Traditional solution: Mutual exclusion**
 - Semaphores, mutexes, spin-locks, disabling interrupts
 - Protects critical sections
 - Drawbacks: blocking, deadlock, priority-inversion, limits parallelism
- **Non-blocking synchronization**
 - Wait-free synchronization [Lamport, 1977]
 - Every operation finishes in a finite number of its own steps.
 - **Lock-free synchronization** [Lamport, 1977]
 - At least one operation in a set of concurrent operation always makes progress.
 - **Obstruction-free synchronization** [Herlihy et. al. 2003]
 - Any operation that eventually executes in isolation is guaranteed to make progress.



Example: Lock-free Stack

- Operations
 - Push(item)
 - Pop: item
- Linked list based algorithm [IBM 1983]

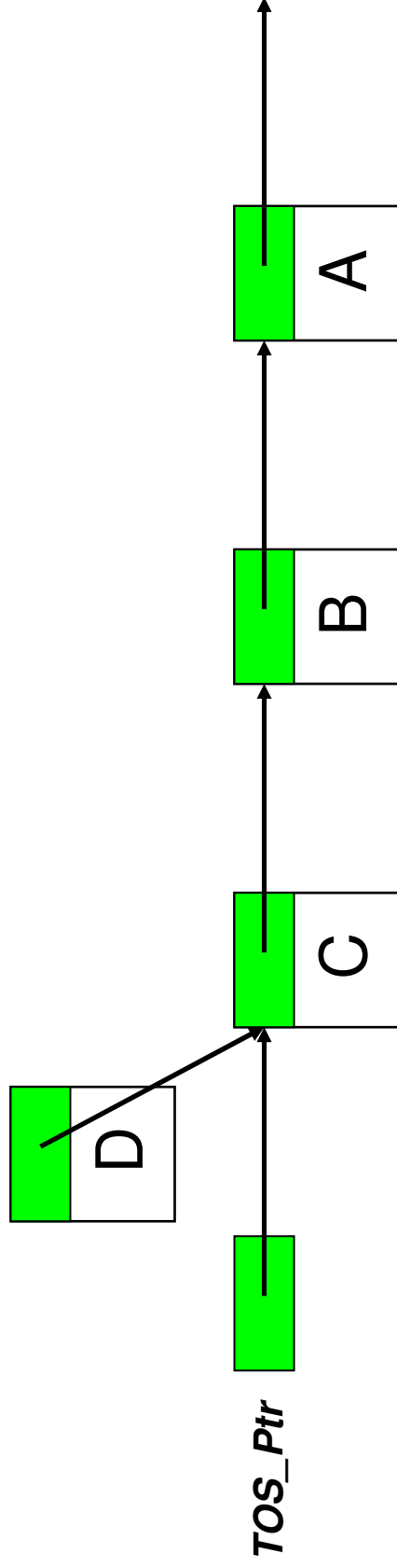


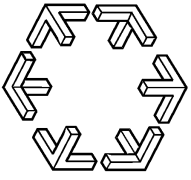


Example: Lock-free Stack

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1. Read *TOS_Ptr*
2. Prepare the new node





Example: Lock-free Stack

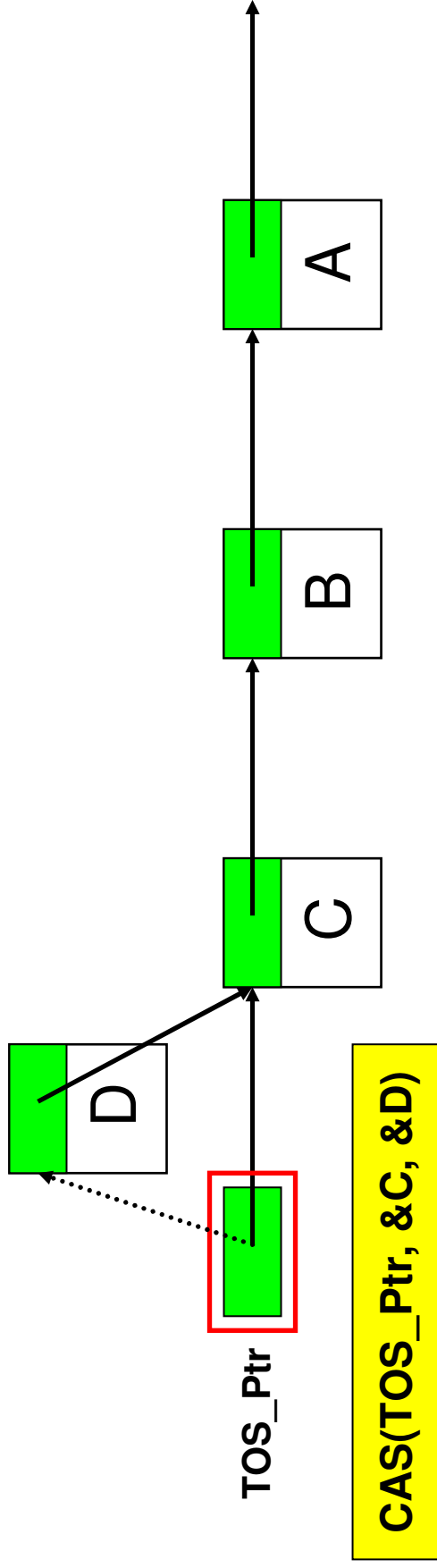
- Operations

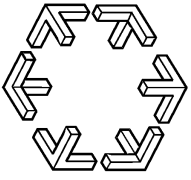
 - Push(item)

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1. Read *TOS_Ptr*
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3. Try to update *TOS_Ptr* with Compare&Swap





Example: Lock-free Stack

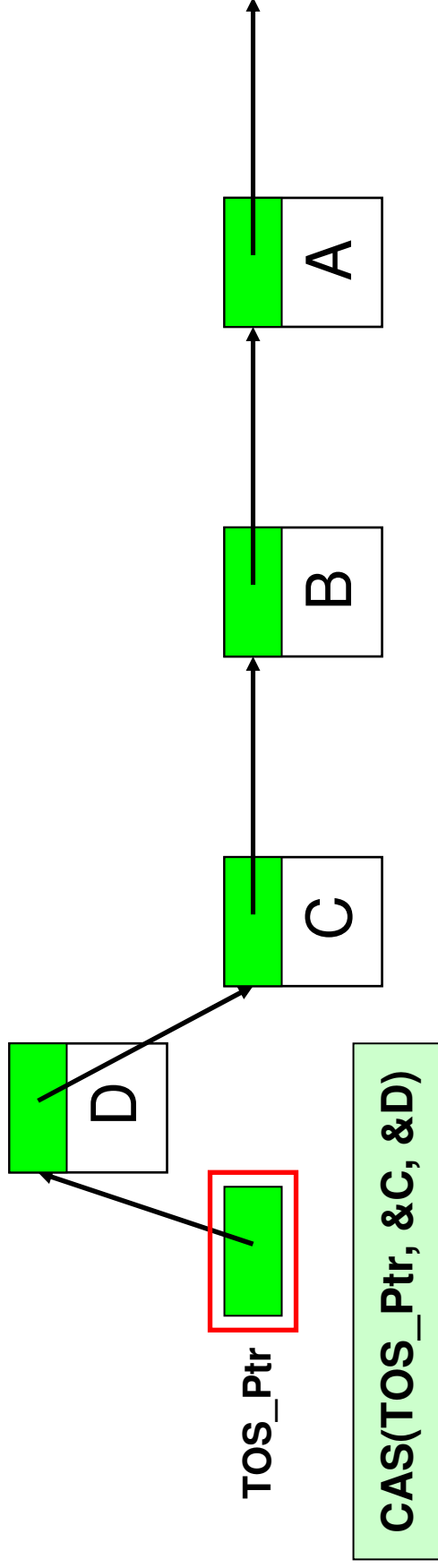
- Operations

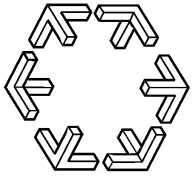
- Push(item)

- Pop: item

- Linked list based algorithm [IBM 1983]

1. Read *TOS_Ptr*
2. Prepare the new node
3. Try to update *TOS_Ptr* with Compare&Swap
4. If successful then done
else retry from 1.

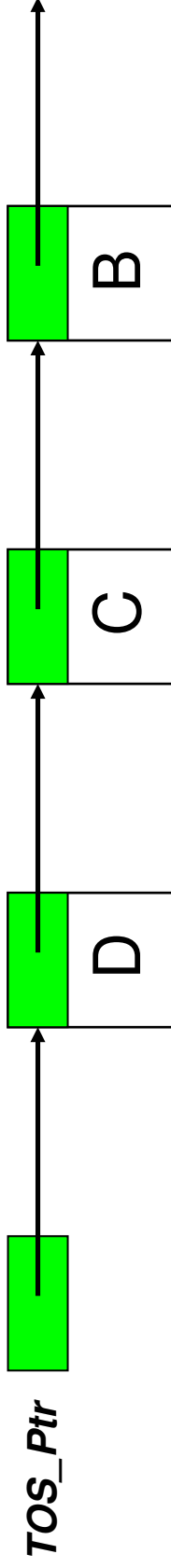


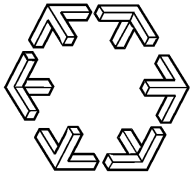


Example: Lock-free Stack

- Operations
 - Push(item)
 - Pop: item
- Linked list based algorithm [IBM 1983]

1. Read *TOS_Ptr*
2. Read *TOS_Ptr->next*





Example: Lock-free Stack

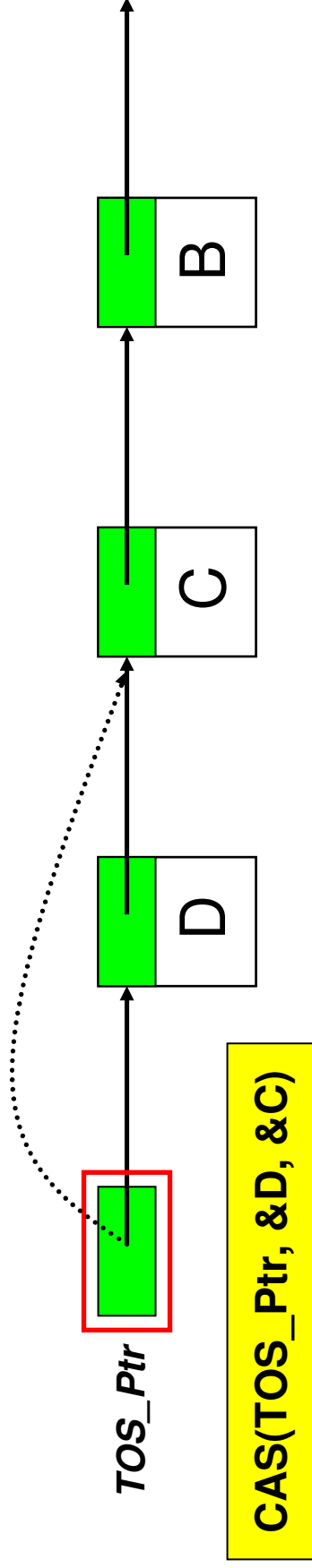
- Operations

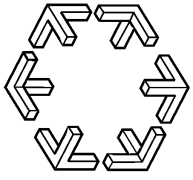
- Push(item)

- Pop: item

- Linked list based algorithm [IBM 1983]

1. Read *TOS_Ptr*
2. Read *TOS_Ptr->next*
3. Try to update *TOS_Ptr* with Compare&Swap





Example: Lock-free Stack

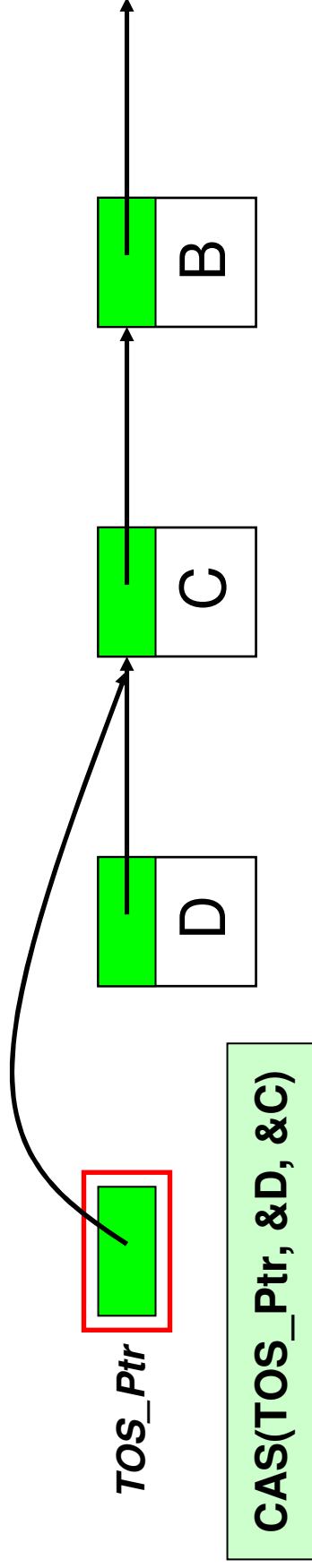
- Operations

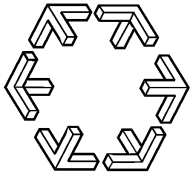
- Push(item)

- Pop: item

- Linked list based algorithm [IBM 1983]

1. Read *TOS_Ptr*
2. Read *TOS_Ptr->next*
3. Try to update *TOS_Ptr* with Compare&Swap
4. If successful then delete the node and return the item else retry from 1.





Example: Lock-free Stack

- Operations

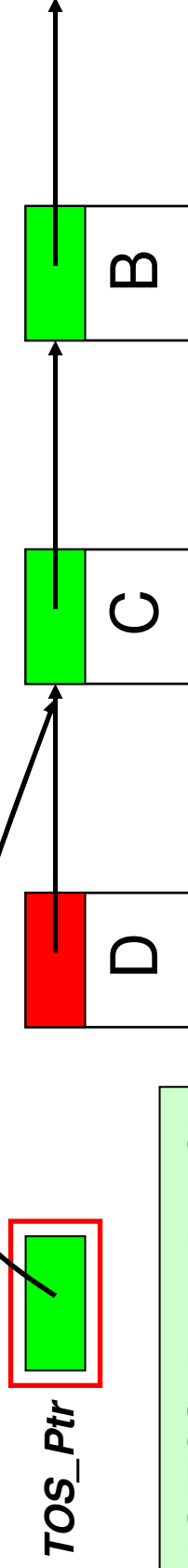
- Push(item)

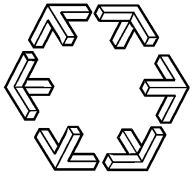
- Pop: item

- Linked list based algorithm [IBM 1983]

But is it safe to delete node D now?

1. Read TOS_Ptr
2. Read $TOS_Ptr \rightarrow next$
3. Try to update TOS_Ptr with Compare&Swap
4. If successful then **delete** the node and return the item else retry from 1.

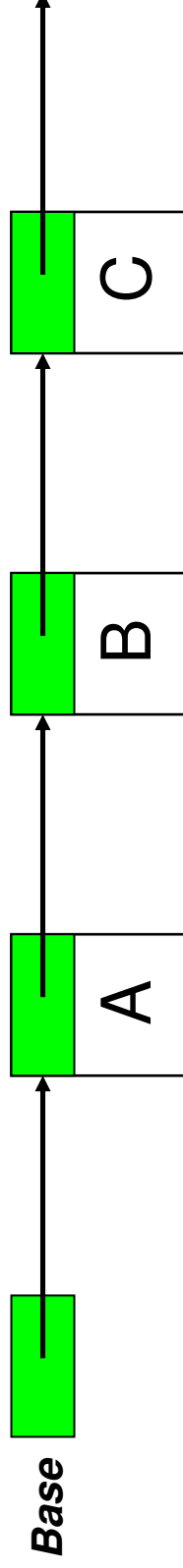


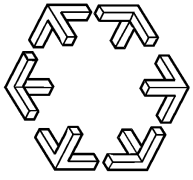


The Lock-Free Memory Reclamation Problem

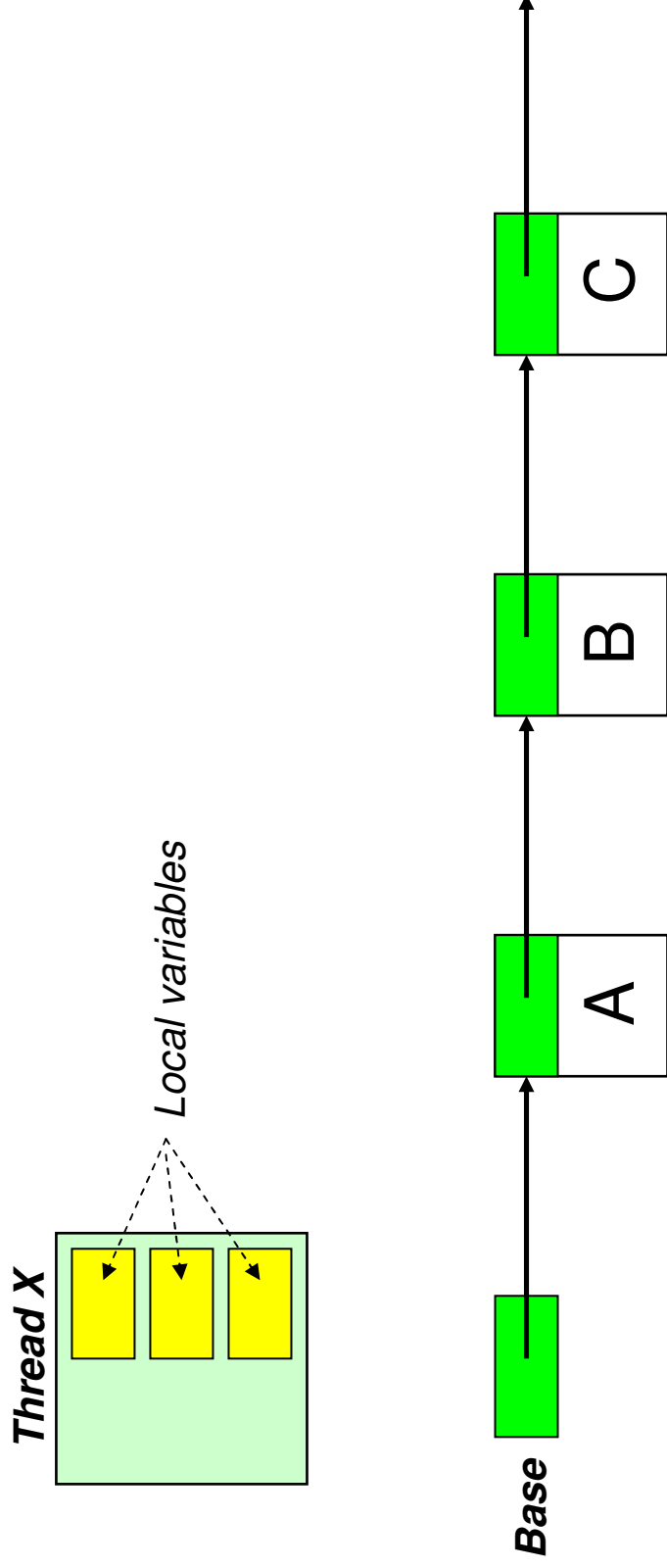
- Concurrent shared data structures with
 - Dynamic use of shared memory
 - Concurrent and overlapping operations by threads or processes

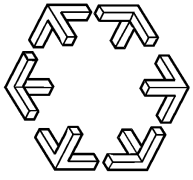
Can nodes be deleted and reused safely?



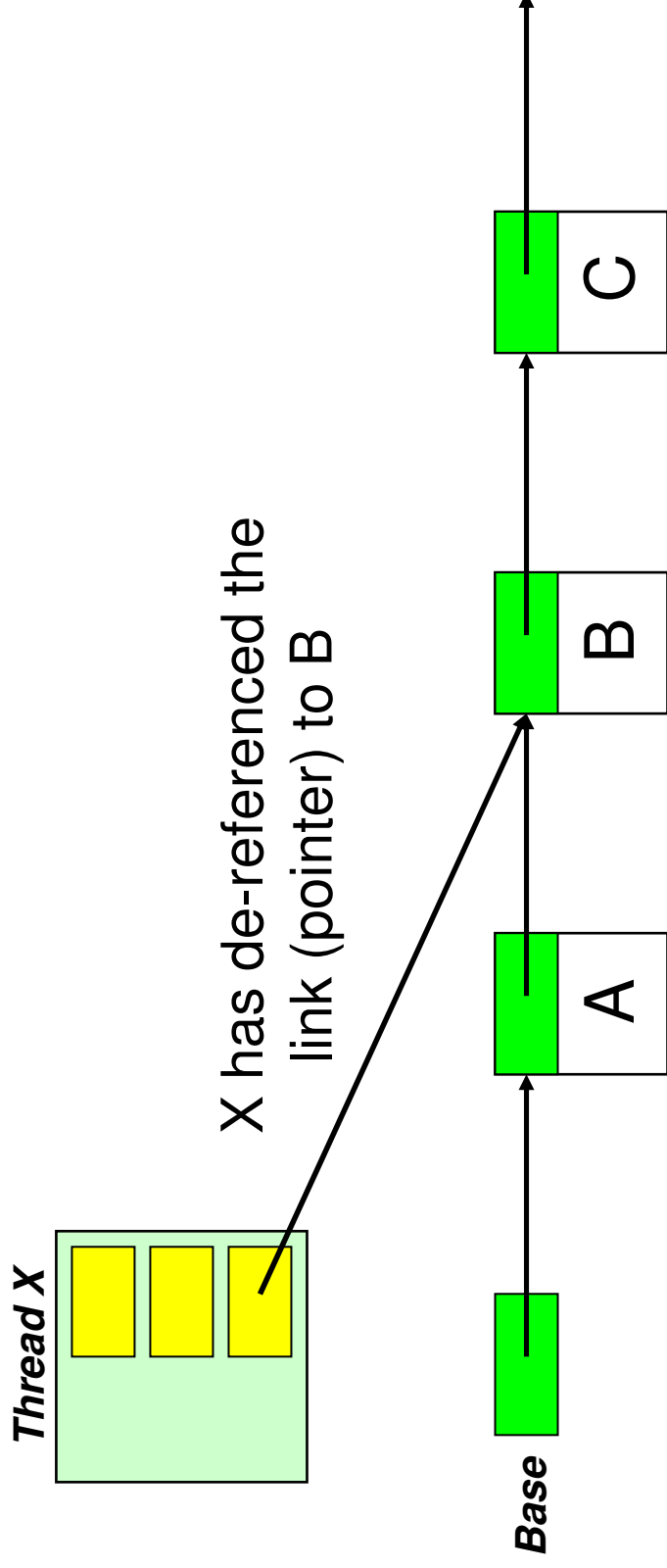


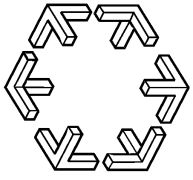
The Lock-Free Memory Reclamation Problem



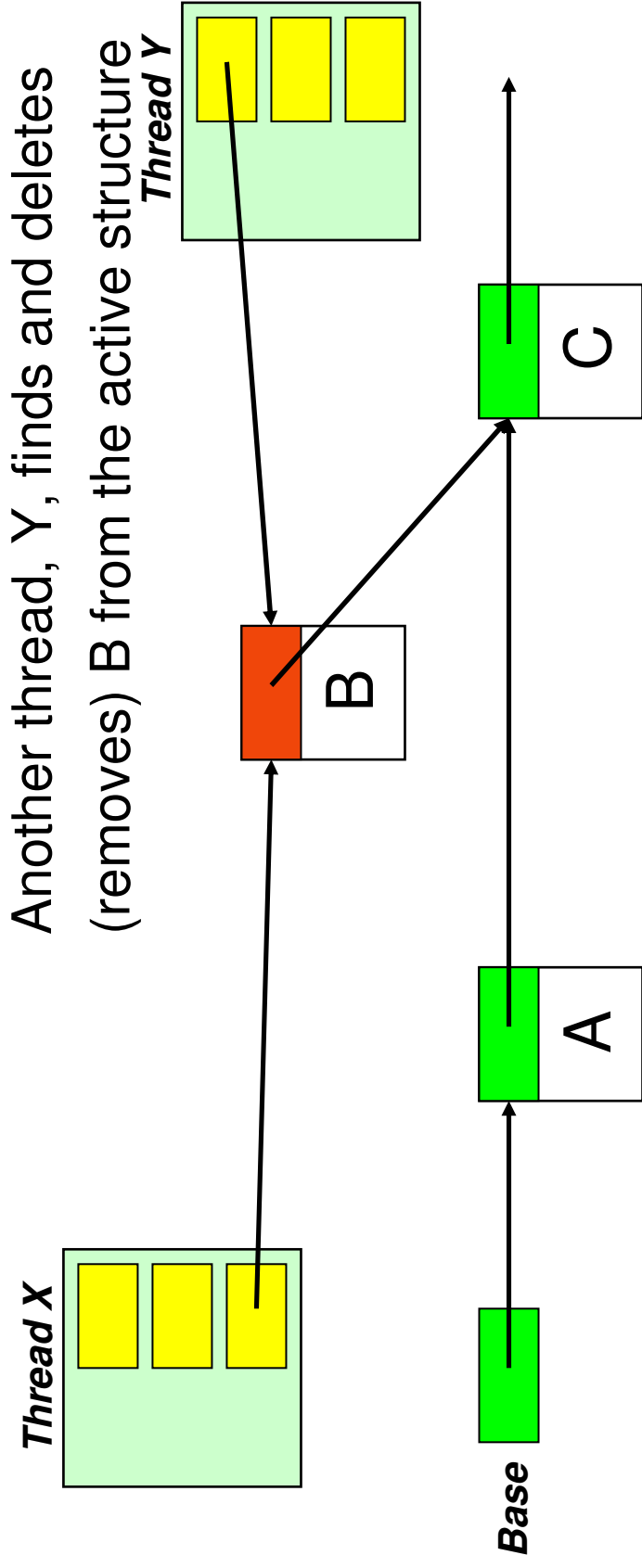


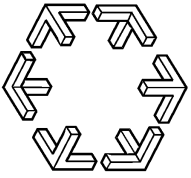
The Lock-Free Memory Reclamation Problem





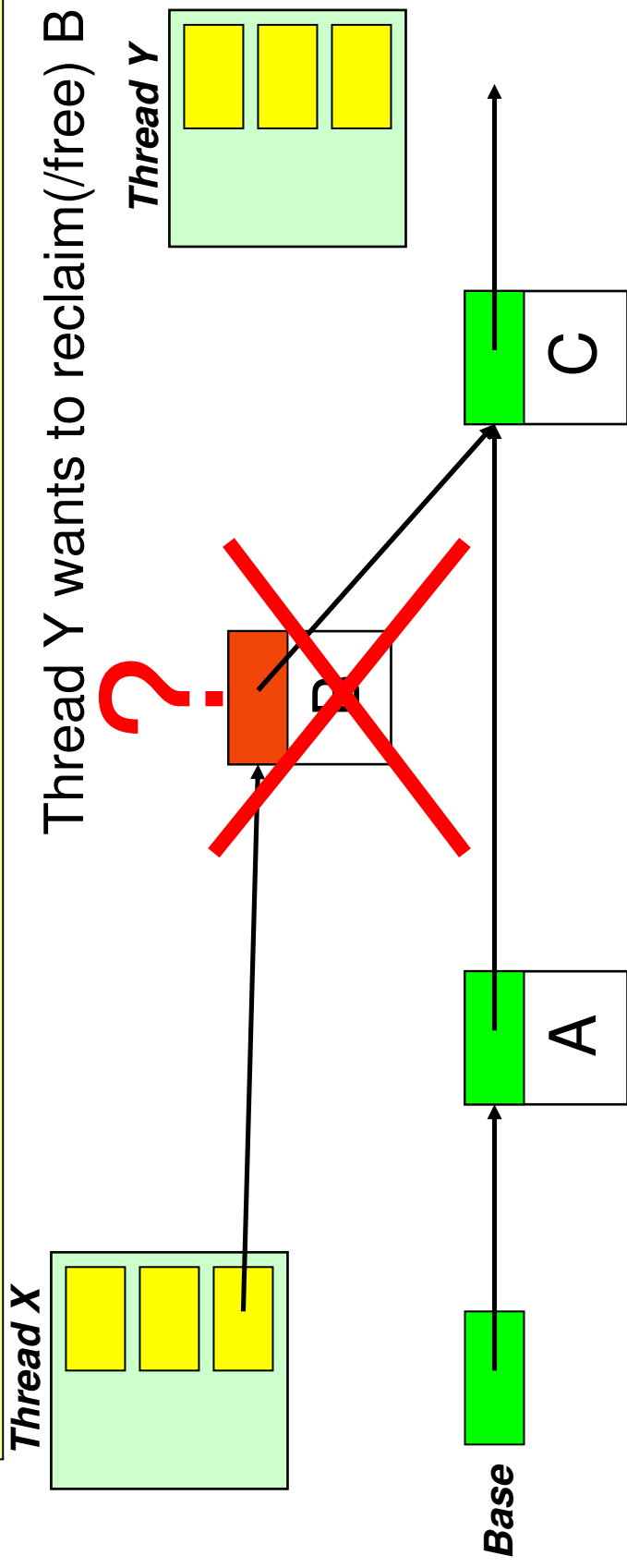
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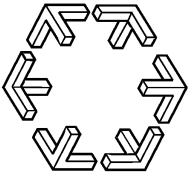




The Lock-Free Memory Reclamation Problem

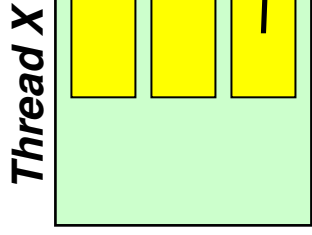
Property I: A node accessible via a private reference (i.e. dereferenced) should not be reclaimed





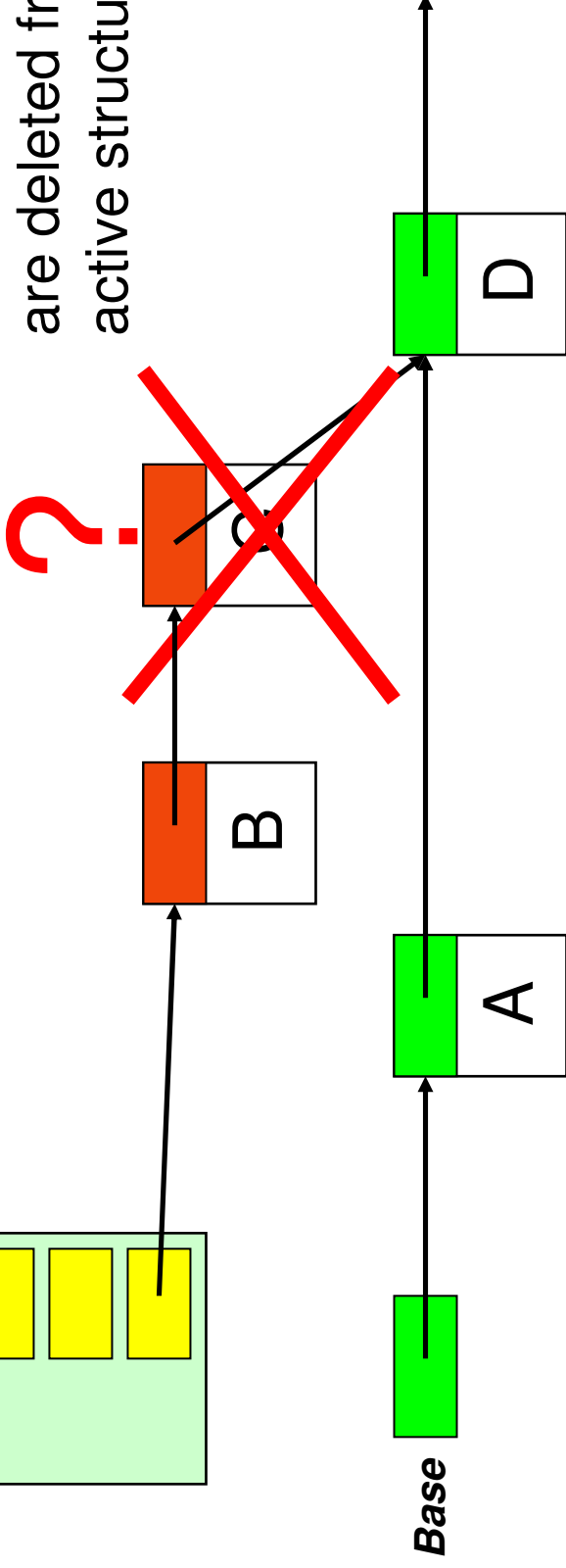
The Lock-Free Memory Reclamation Problem

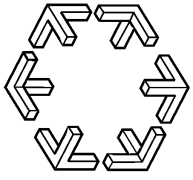
Property II: Links in a dereferenced node should always be dereferencable.



Thread X

The nodes B and C are deleted from the active structure.

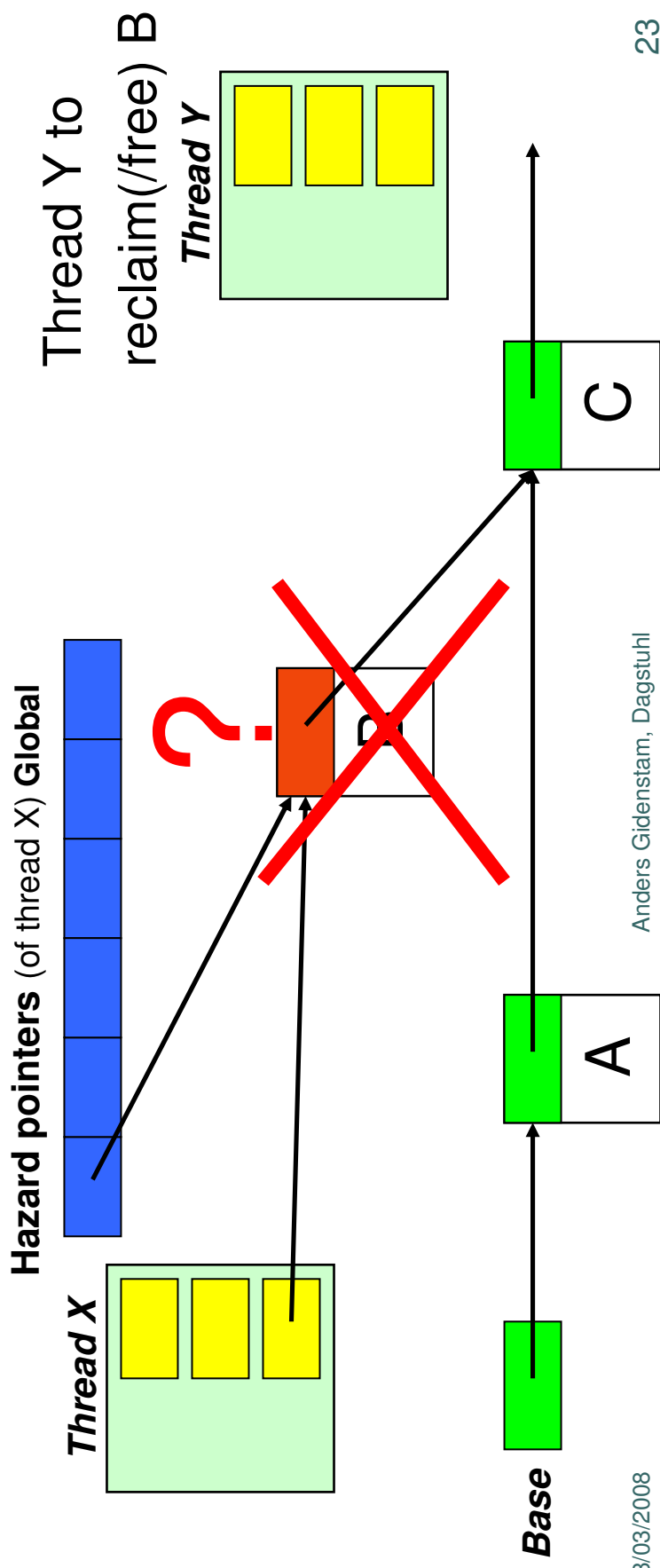


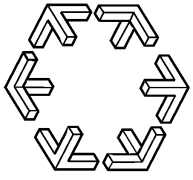


The Lock-Free Memory Reclamation Problem

Solutions providing Property I but not Property II:

- Hazard Pointers [Michael 2002]
- Pass the Buck [Herlihy 2002]



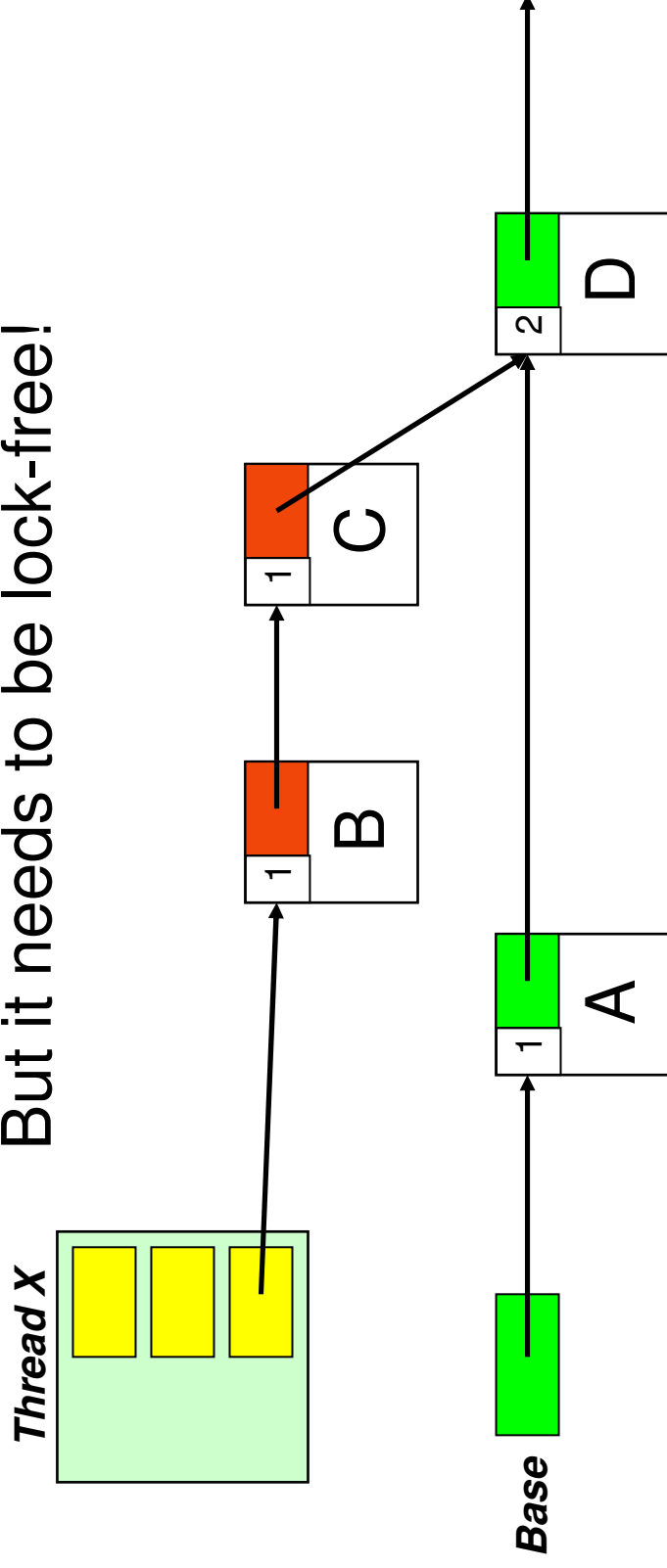


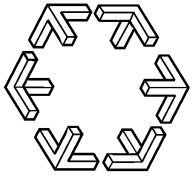
The Lock-Free Memory Reclamation Problem

Reference counting can guarantee

- Property I
- Property II

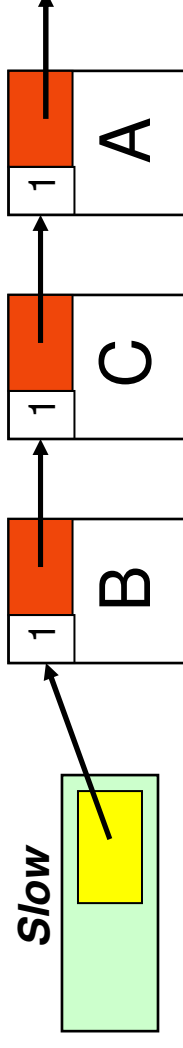
But it needs to be lock-free!

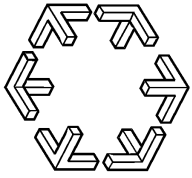




Lock-free reference counting solutions

- [Valois et al, 1995] Reference-count field MUST remain writable forever.
- LFRC [Detlefs et al, 2001] Needs double word CAS.
- SLFRC [Herlihy et al, 2002/2005] Pure reference counting (RC).
- LFMR [Gidenstam et al, 2005] RC + application guidance.
- Issues with pure reference counting
 - A slow thread with a private reference might prevent reclamation
 - Cyclic garbage

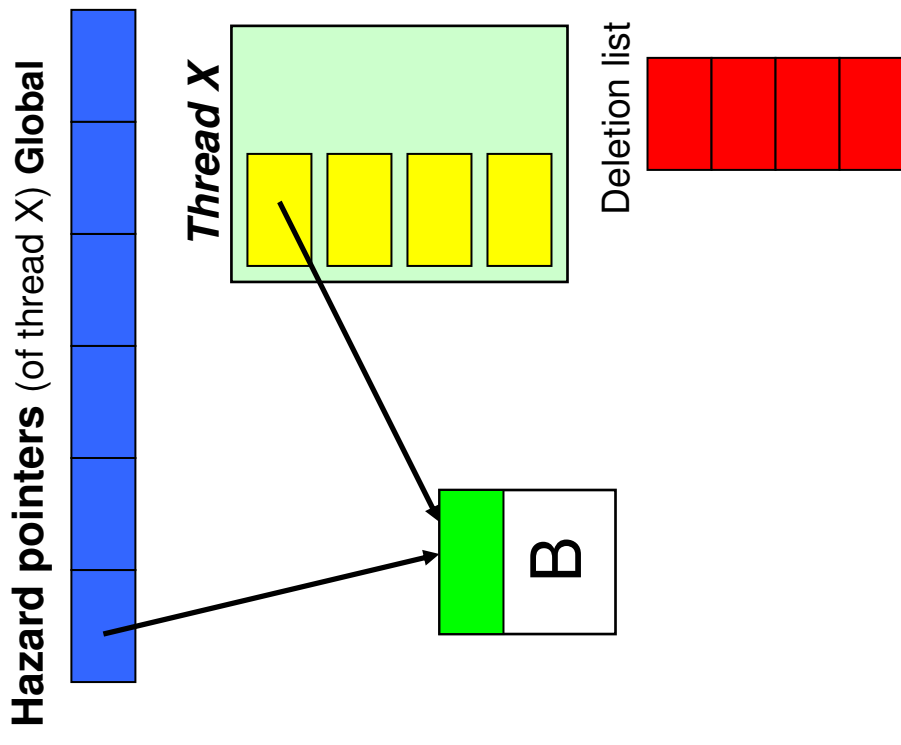


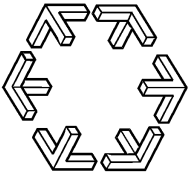


Our approach – The basic idea

Joint work w. M. Papatriantafilou, H. Sundell & P. Tsigas

- Combine the best of
 - Hazard pointers [Michael 2002]
 - Tracks references from threads
 - Fast de-reference
 - Upper bound on the number of unreclaimed deleted nodes
 - Compatible with standard memory allocators

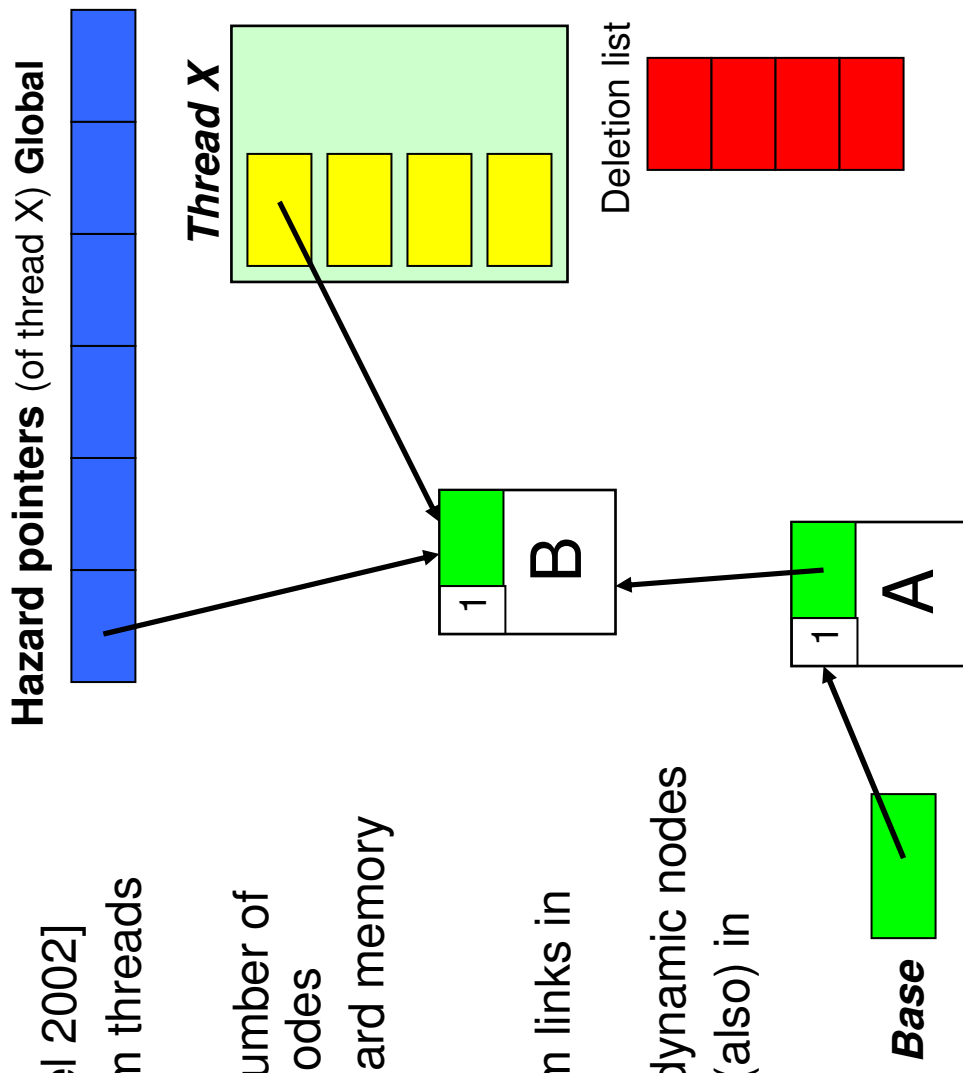


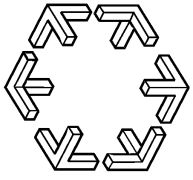


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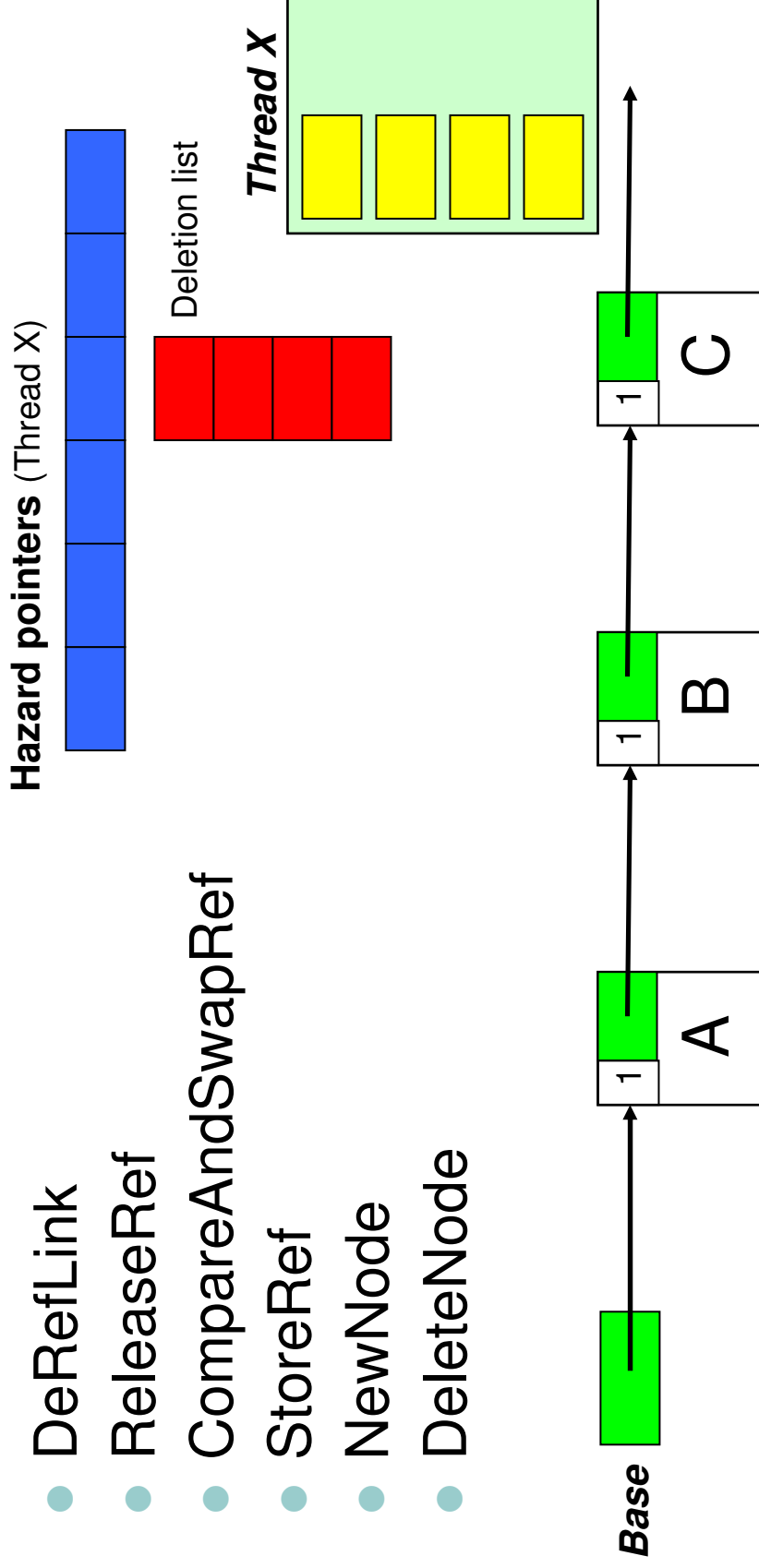
- Combine the best of
 - Hazard pointers [Michael 2002]
 - Tracks references from threads
 - Fast de-reference
 - Upper bound on the number of unreclaimed deleted nodes
 - Compatible with standard memory allocators
 - Reference counting
 - Tracks references from links in shared memory
 - Manages links within dynamic nodes
 - Safe to traverse links (also) in deleted nodes

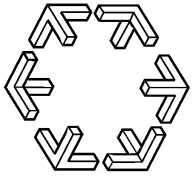




The basic idea

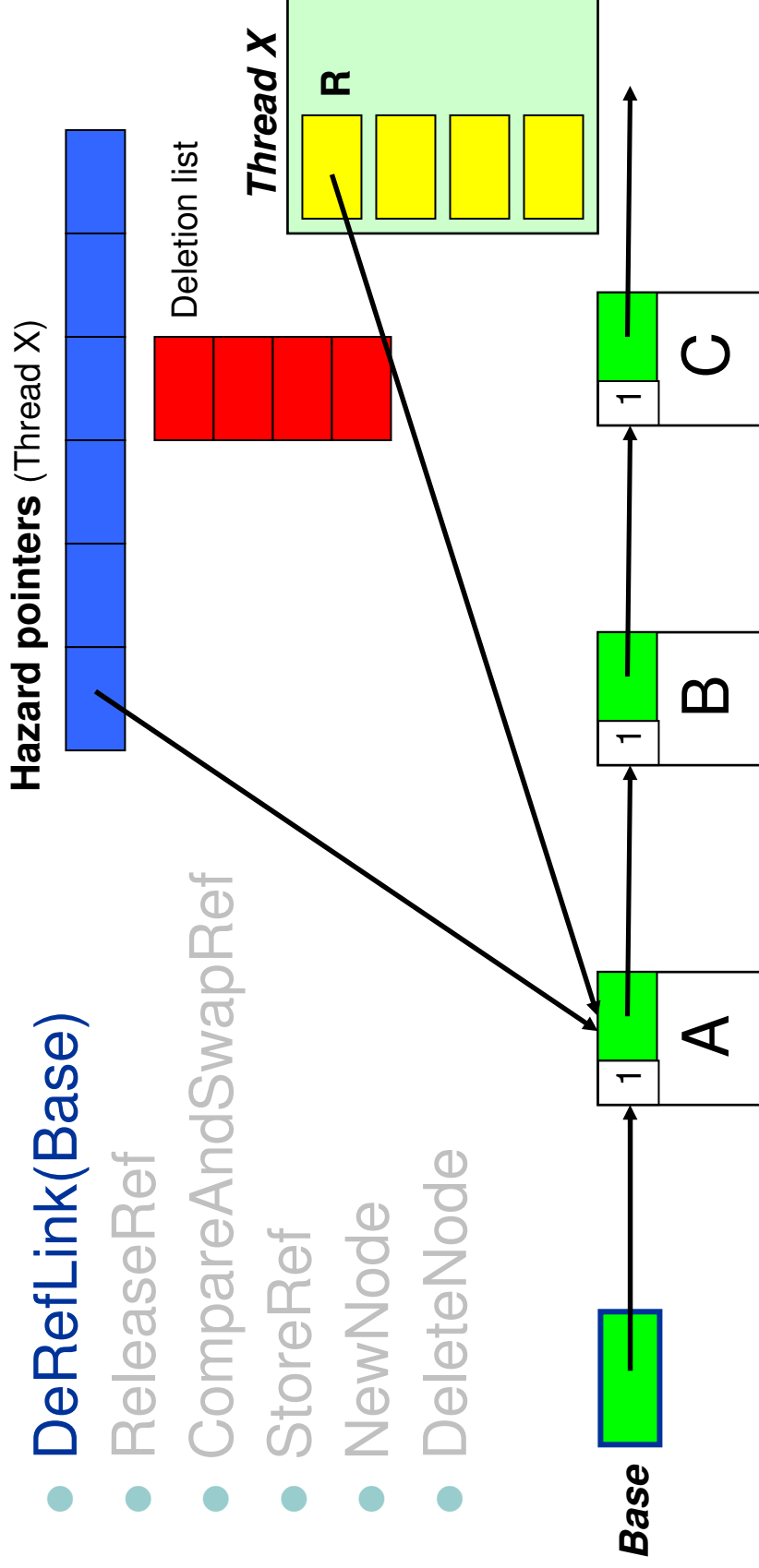
- API
 - DeRefLink
 - ReleaseRef
 - CompareAndSwapRef
 - StoreRef
 - NewNode
 - DeleteNode

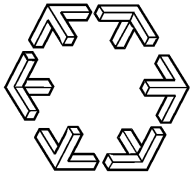




The basic idea

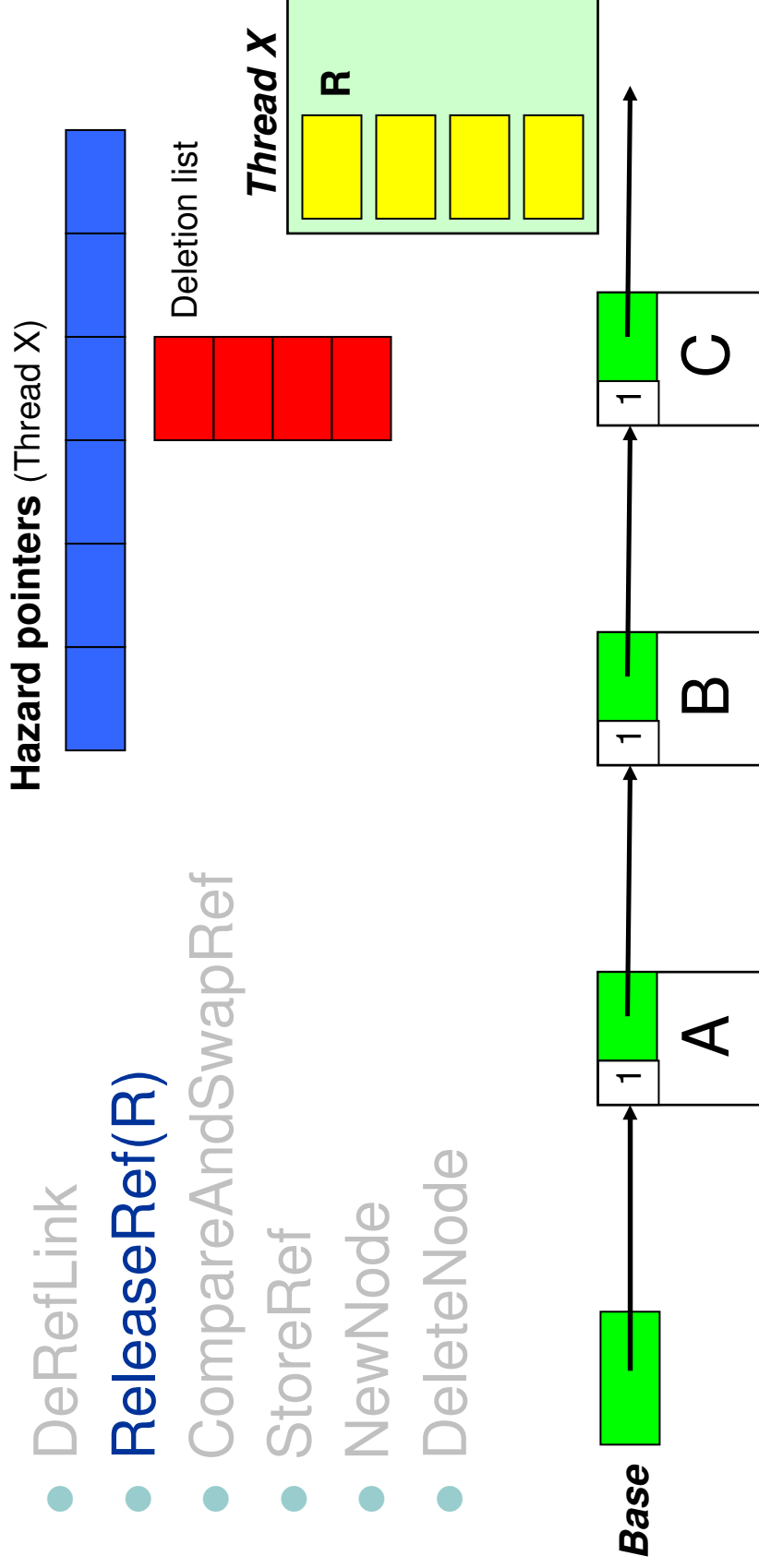
- API
 - DeRefLink(Base)
 - ReleaseRef
 - CompareAndSwapRef
 - StoreRef
 - NewNode
 - DeleteNode

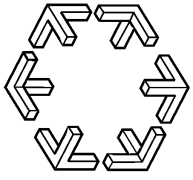




The basic idea

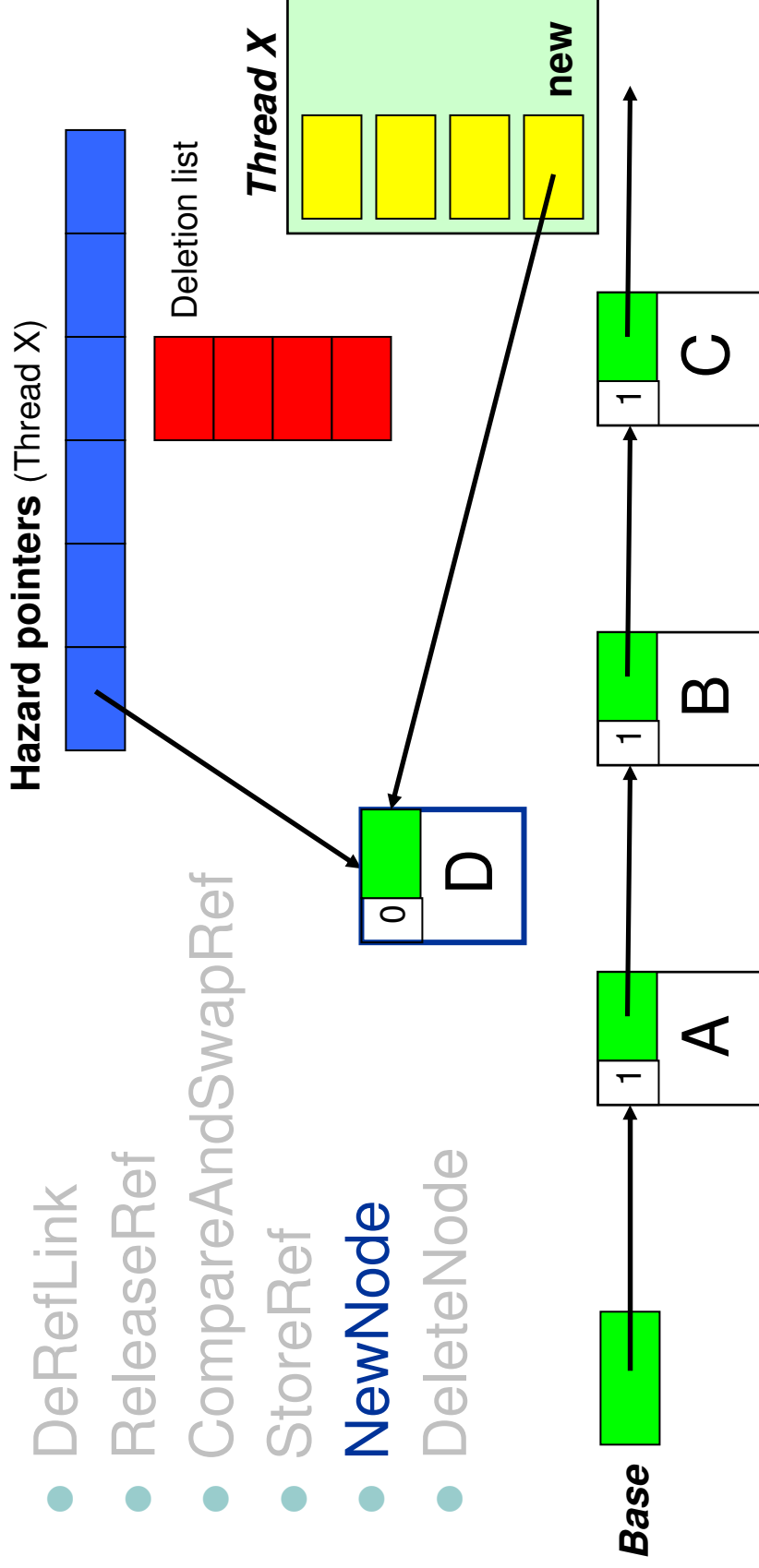
- API
 - DeRefLink
 - **ReleaseRef(R)**
 - CompareAndSwapRef
 - StoreRef
 - NewNode
 - DeleteNode

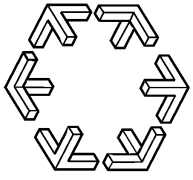




The basic idea

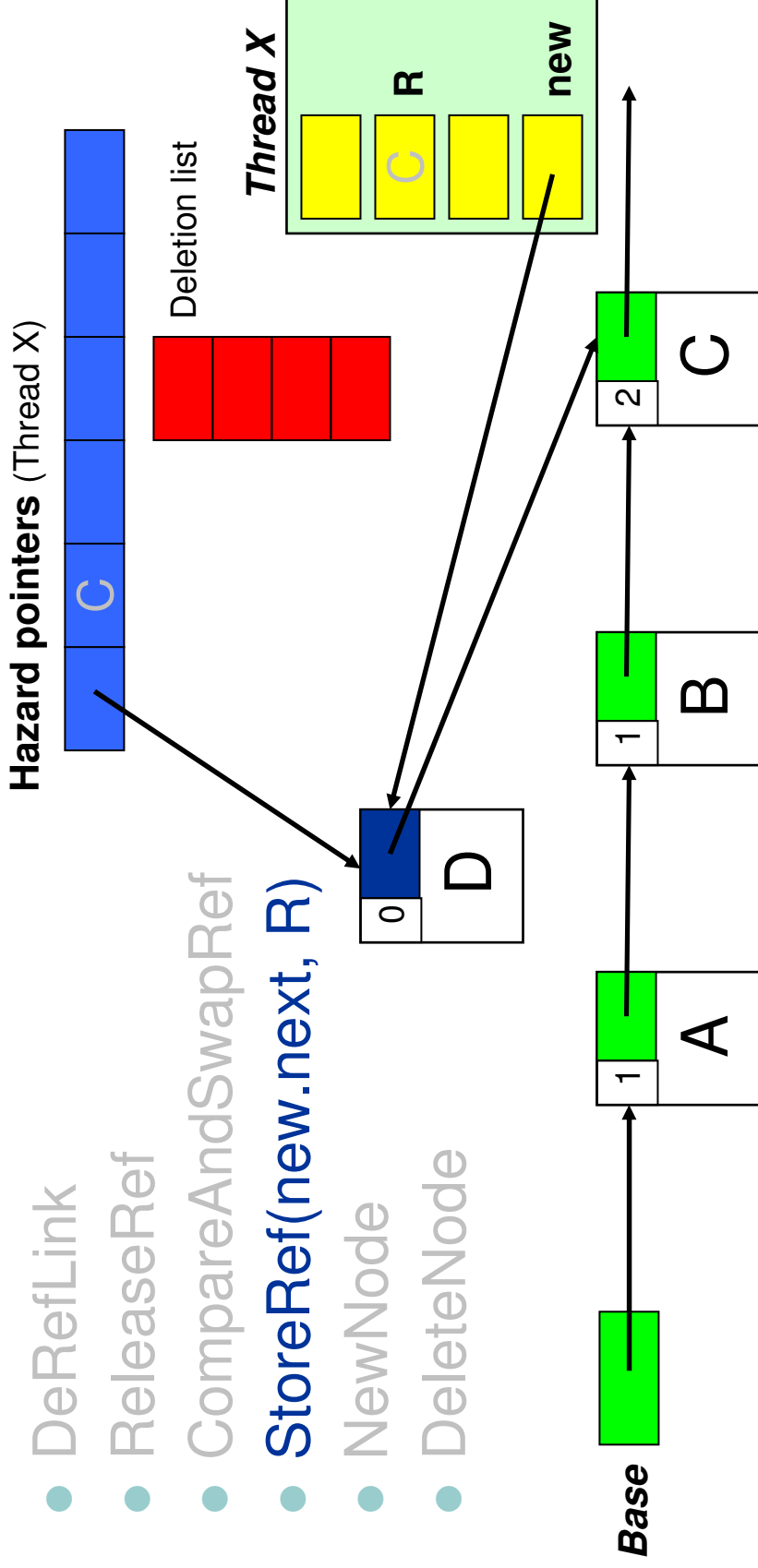
- API
 - DeRefLink
 - ReleaseRef
 - CompareAndSwapRef
 - StoreRef
 - **NewNode**
 - DeleteNode

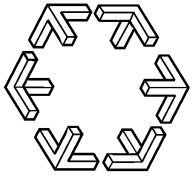




The basic idea

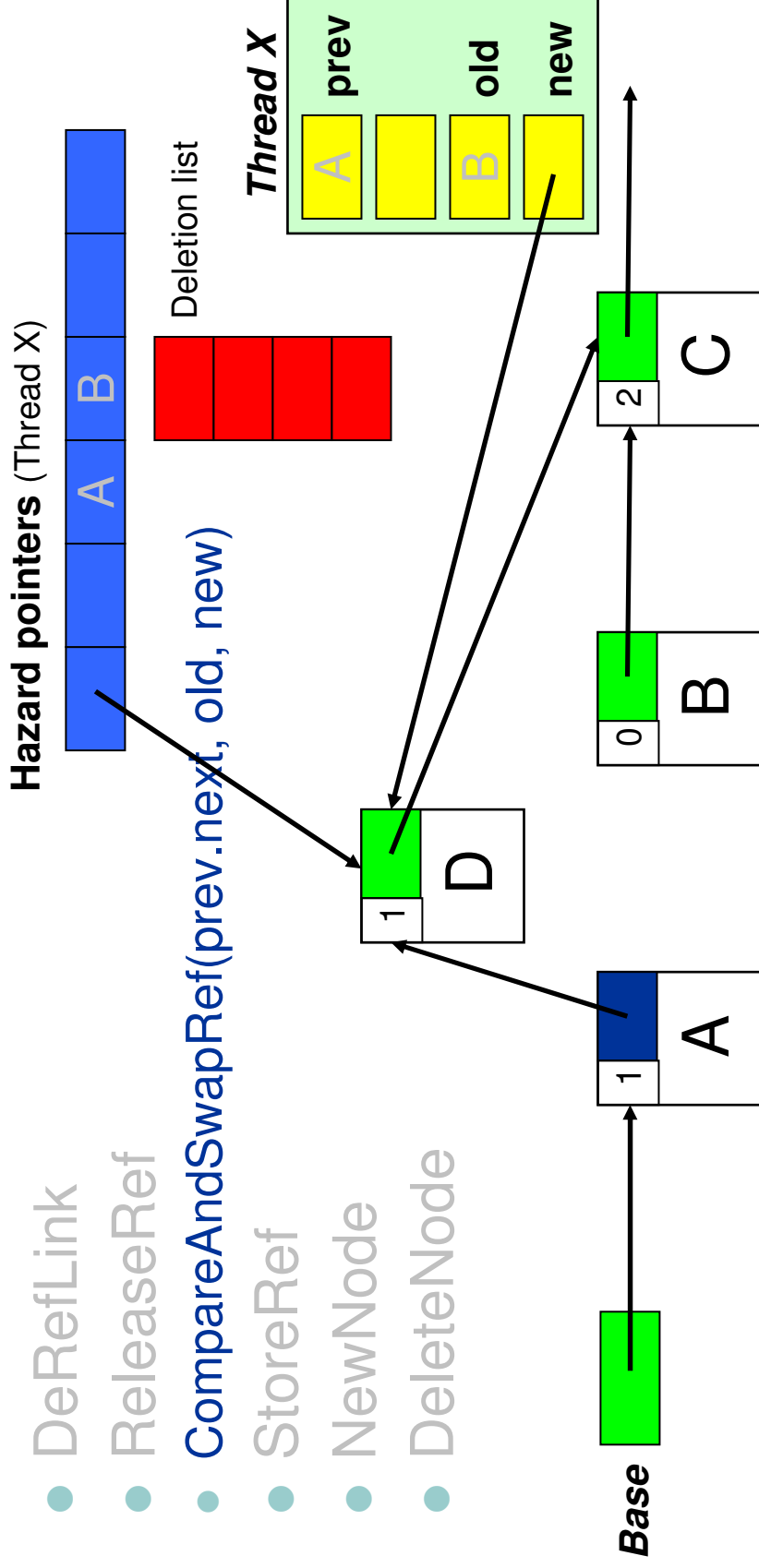
- API
 - DeRefLink
 - ReleaseRef
 - CompareAndSwapRef
 - **StoreRef(new.next, R)**
 - NewNode
 - DeleteNode

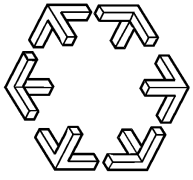




The basic idea

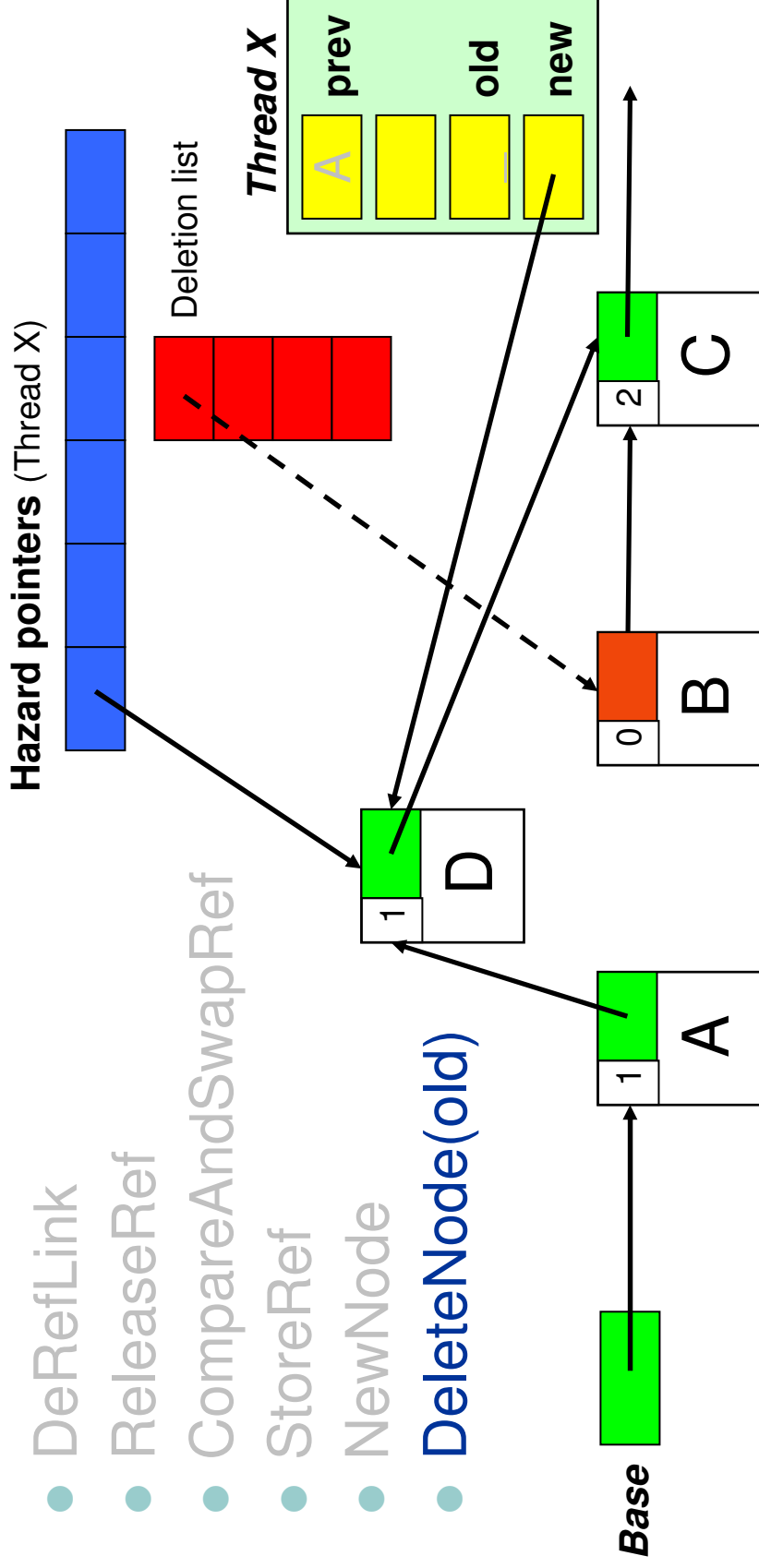
- API
 - DeRefLink
 - ReleaseRef
 - CompareAndSwapRef(prev.next, old, new)
 - StoreRef
 - NewNode
 - DeleteNode

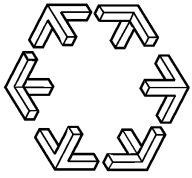




The basic idea

- API
 - DeRefLink
 - ReleaseRef
 - CompareAndSwapRef
 - StoreRef
 - NewNode
 - DeleteNode(old)





Bound on #unreclaimed nodes

Theorem: The maximum number of deleted but not yet reclaimed nodes in the system is never more than

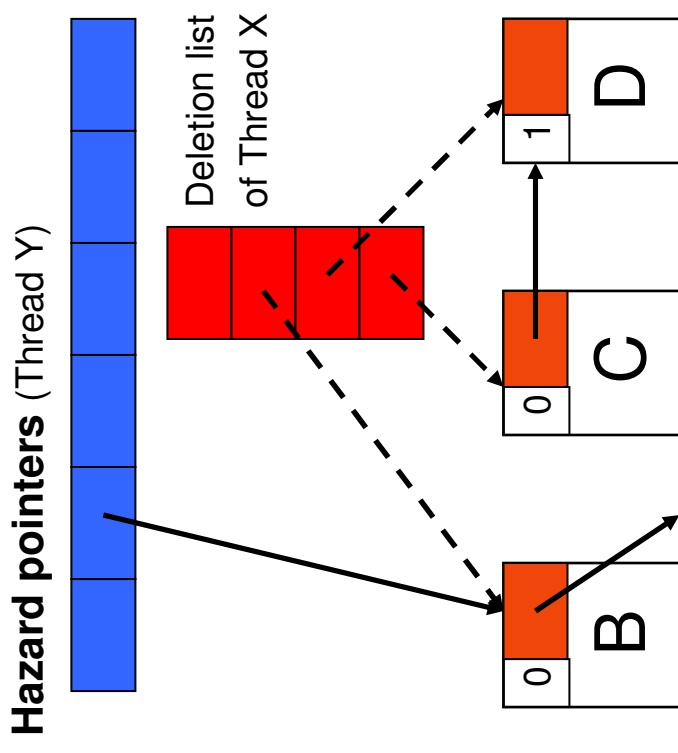
$$N^2 \cdot (k + l_{\max} + a + 1)$$

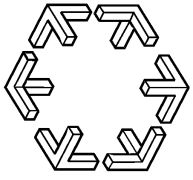
where

N is the number of threads in the system,
 k is the number of hazard pointers per thread,

l_{\max} is the maximum number of links a node can contain and

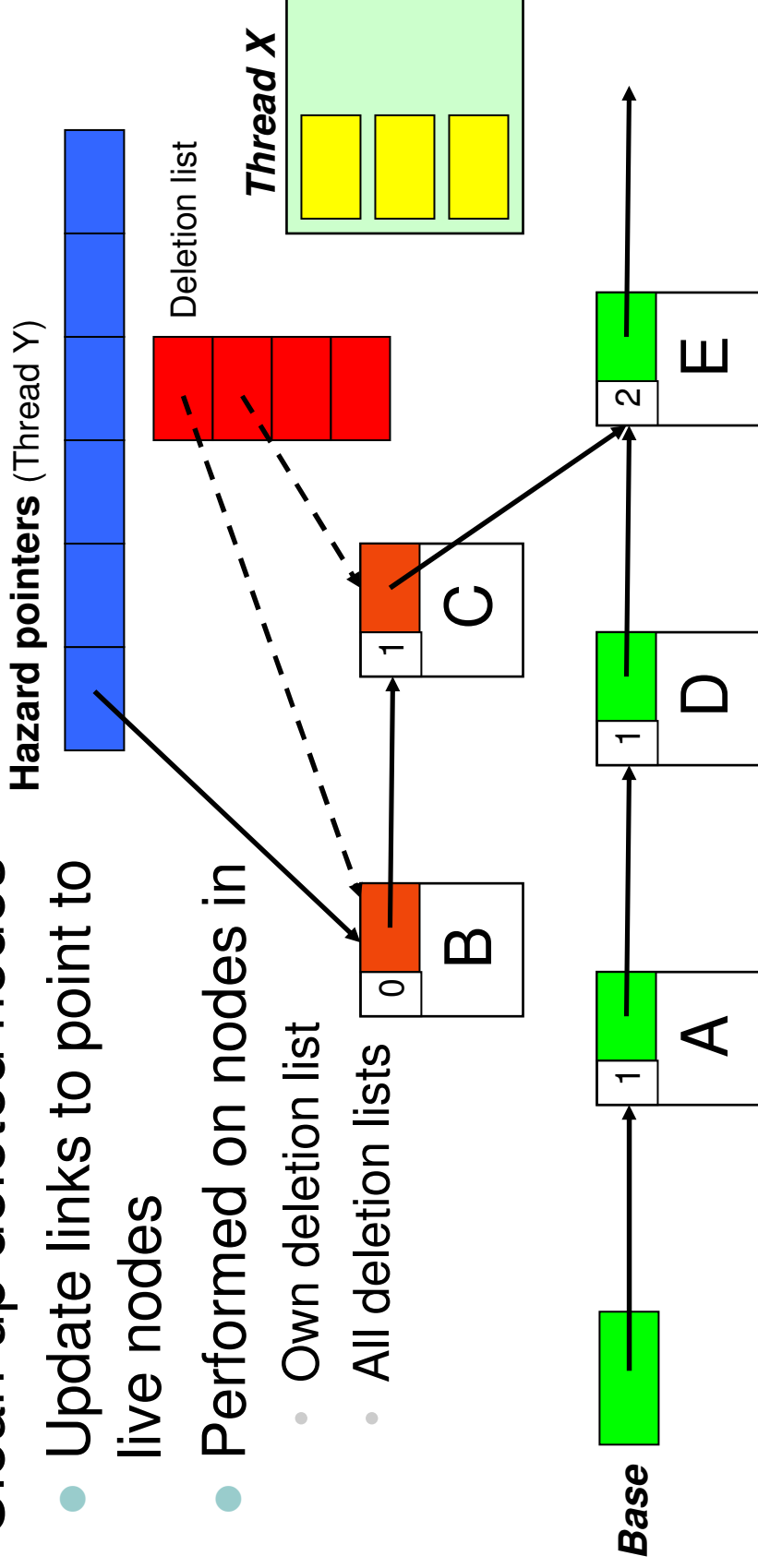
a is the maximum number of links in live nodes that may transiently point to a deleted node during an operation.

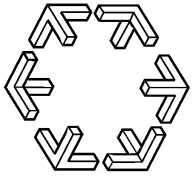




Breaking chains of garbage

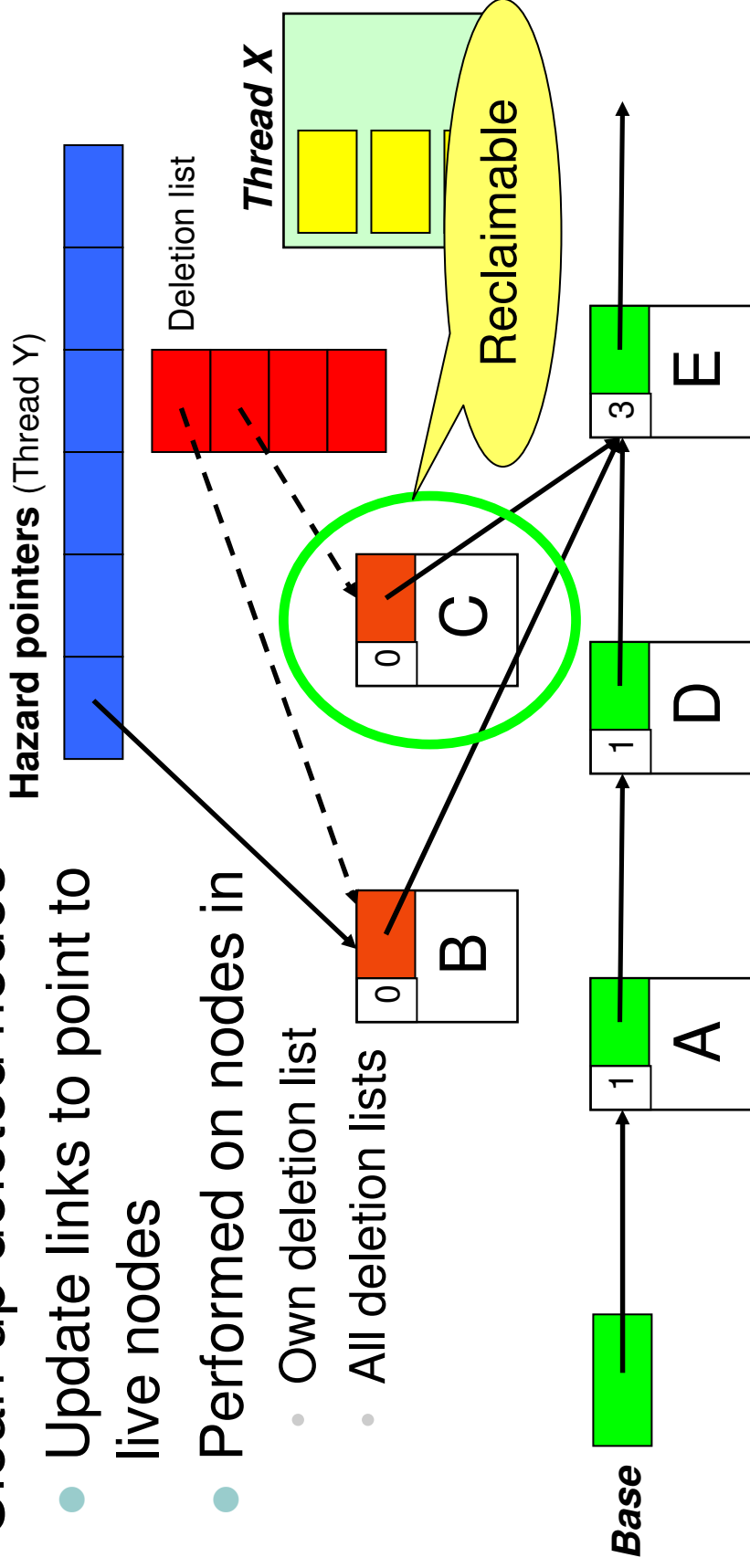
- Clean-up deleted nodes
 - Update links to point to live nodes
 - Performed on nodes in
 - Own deletion list
 - All deletion lists

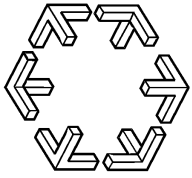




Breaking chains of garbage

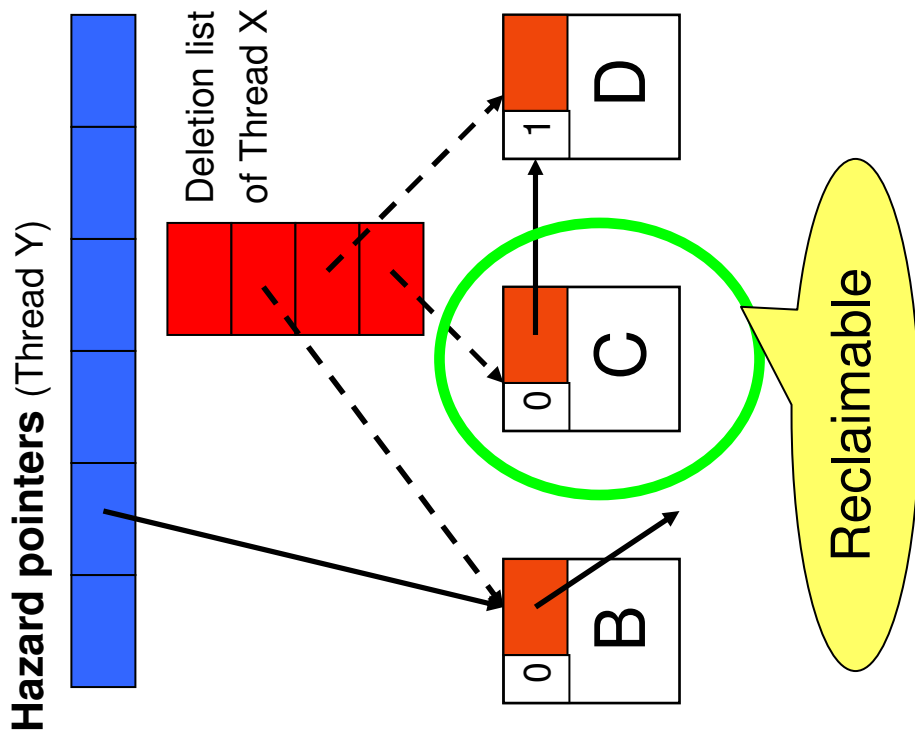
- Clean-up deleted nodes
 - Update links to point to live nodes
 - Performed on nodes in
 - Own deletion list
 - All deletion lists

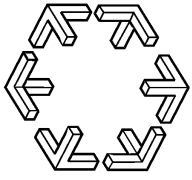




Bound on #unreclaimed nodes

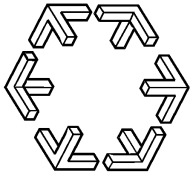
- A deleted node is unreclaimable if
 - A hazard pointer points to it
 - Limited #hazard pointers: $N \cdot k$
 - Its reference count is nonzero
 - Limited #links in live nodes pointing to deleted nodes: $N \cdot a$
 - The links in most deleted nodes can be cleaned by any process.
Exception: each thread can "hide" one node during a Delete operation.
 - #links in any node is bounded
 $\Rightarrow N \cdot l_{max}$
 - It is being cleaned by another thread: $N \cdot 1$
- \Rightarrow The maximum size of a thread's deletion list is bounded by
- $$N \cdot (k + l_{max} + a + 1)$$
- \Rightarrow The total number of unreclaimable deleted nodes is bounded by
- $$N^2 \cdot (k + l_{max} + a + 1)$$



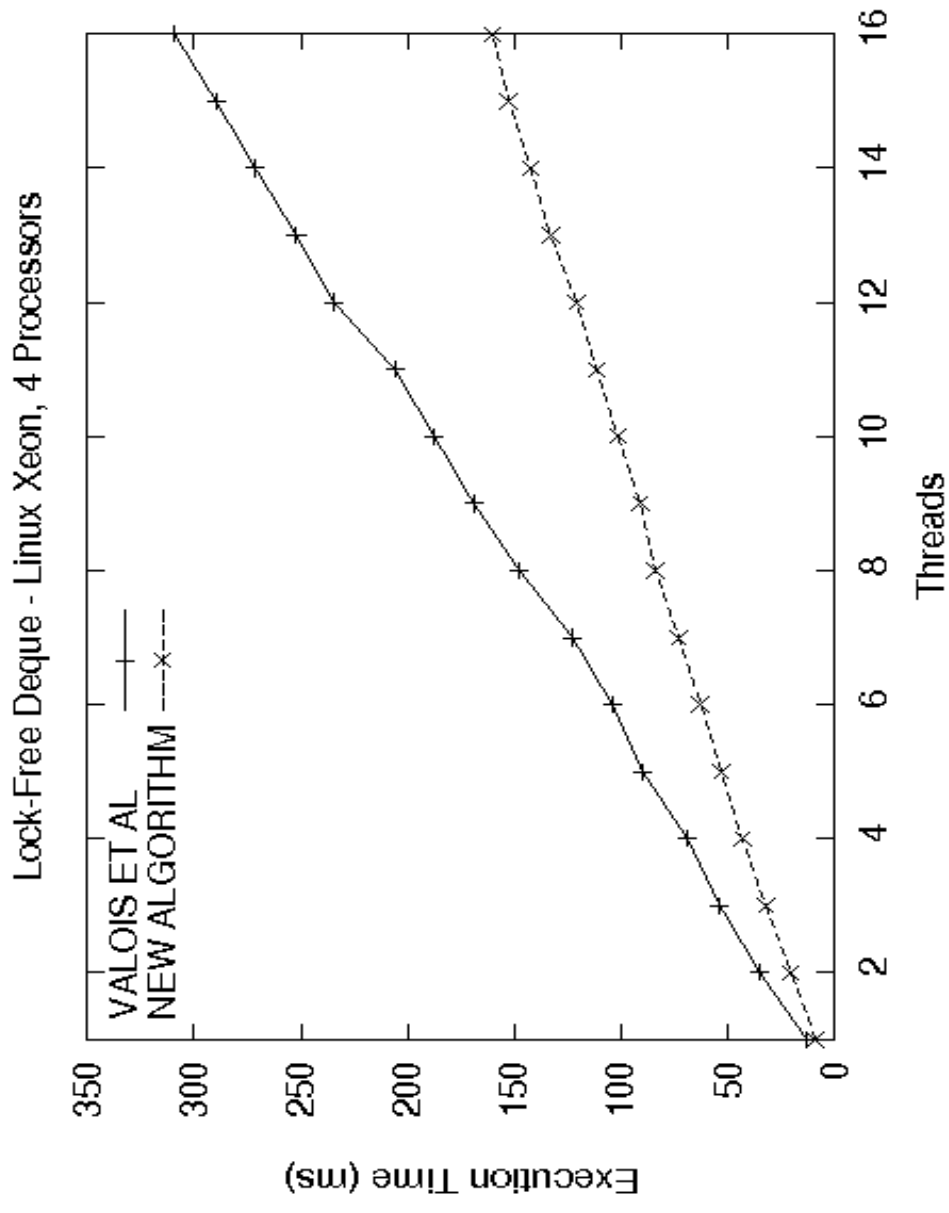


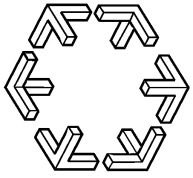
Experimental evaluation

- Lock-free deque [Sundell and Tsigas 2004]
(deque – double-ended queue)
 - The algorithm needs traversal of deleted nodes
 - Time for 10000 random operations/thread
- Tested memory reclamation schemes
 - Reference counting, Valois et al.
 - LFRM (a.k.a. the new algorithm)
- Systems
 - 4 processor Xeon PC / Linux (UMA)
 - 8 processor SGI Origin 2000 / IRIX (NUMA)

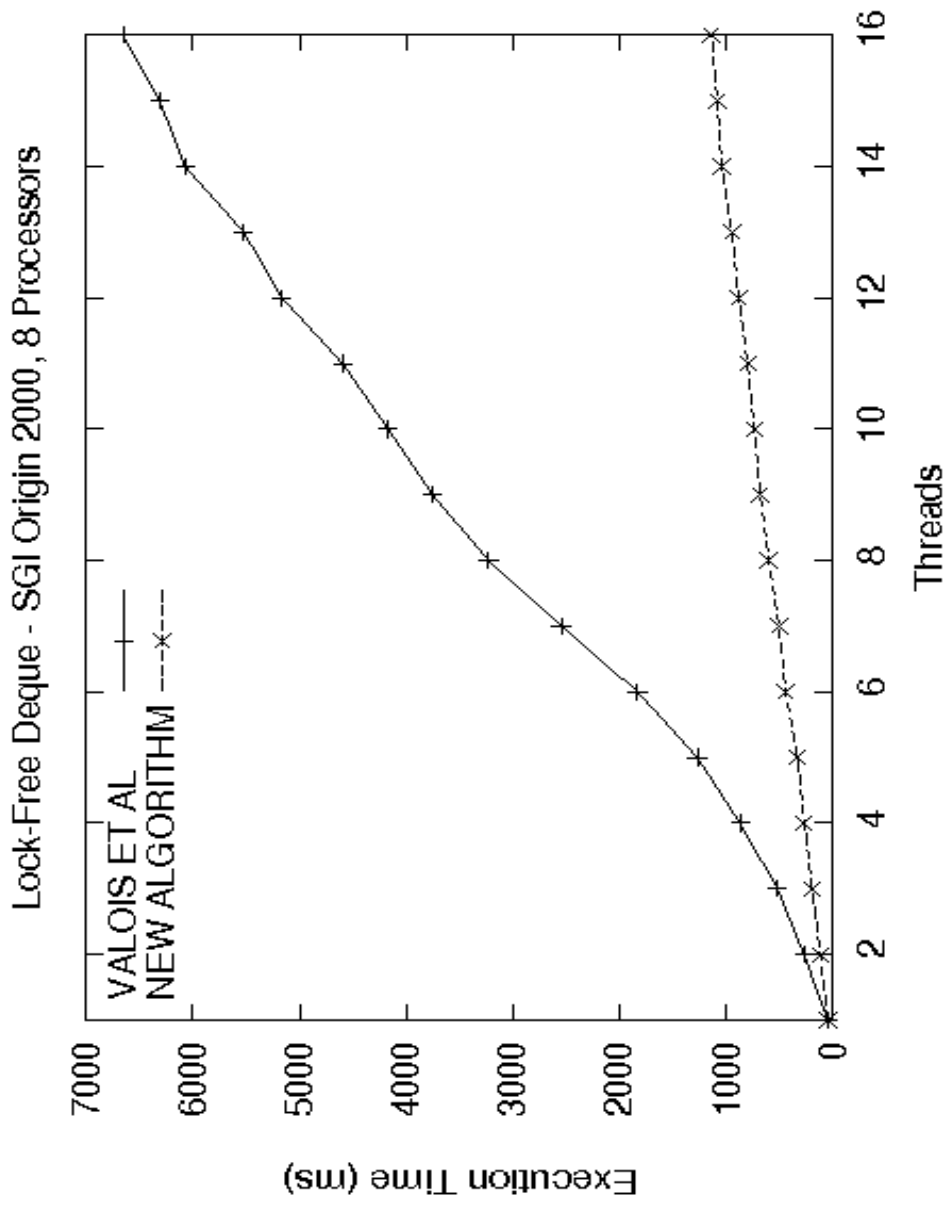


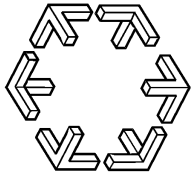
Experimental evaluation





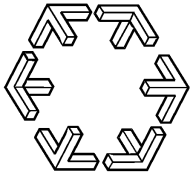
Experimental evaluation





Some lock-free data-structures

Stacks	Memory man.	Linked lists	Memory man.
[IBM 1983],[Treiber, 1986]	version #s / HP	[Valois, 1995]	RC
Queues		[Harris, 2001]	RC
[Valois, 1994]	RC	Doubly linked lists	
[MS, 1996]	RC / HP	[TS, 2007]	RC
[TZ, 2001]	bounded size	Hash tables	
[Hoffman et al, 2007]	version #s / RC	[Michael, 2002]	HP
Double Ended Queues / Deques		[Shalev Shavit 2006]	?
[M, ?]	?	Trees (Binary, Red-Black)	
[ST, 2004]	RC	[Fraser, 2004]	M-CAS / STM / RC
Priority Queues			
[Barnes, 1994]	bounded size		
[ST 2003]	RC		
Sets/Dictionaryes			
[Michael, 2002]	HP		
[TS 2004]	RC		



Current Work

- Memory management
 - Unified and easy to use interfaces to the memory management algorithms [NBAda library]
 - Easier to implement lock-free data-structures
 - Data-structure user could choose memory management method.
- Lock-free data-structures
 - Develop new (Red-Black trees with 1-CAS?)
 - Software library: NBAda
 - Ought to be here: <http://www.mpi-inf.mpg.de/~andersg/>
For now: Ask me.